Langevin dynamics of fluctuation-induced first-order phase transitions: Self-consistent Hartree approximation

Roberto Mulet1 and Daniel A. Stariolo2

1“Henri-Poincaré-Group” of Complex Systems and Department of Theoretical Physics, Physics Faculty, University of Havana, La Habana, CP 10400, Cuba
2Departamento de Fisica, Universidade Federal do Rio Grande do Sul, CP 15051, 91501-970, Porto Alegre, Brazil

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The Langevin dynamics of a system with a scalar-order parameter exhibiting a fluctuation-induced first-order phase transition is solved within the self-consistent Hartree approximation. Competition between interactions on short and long length scales gives rise to spatial modulations in the order parameter, such as stripes in 2d and lamellae in 3d. We show that when the time scale of observation is small compared with the time needed for the formation of modulated structures, the dynamics is dominated by a standard ferromagnetic contribution plus a correction term. However, once these structures are formed, the long-time dynamics is no longer purely ferromagnetic. After a quench from a disordered state to low temperatures, the system develops growing domains of stripes (lamellae). Due to the character of the transition, the paramagnetic phase is metastable at all finite temperatures, and the correlation length diverges only at T=0. Consequently, the temperature is a relevant variable: for T>0 the system ends up forming domains of stripes with a finite correlation length while for T=0 a scaling behavior in space and time, characteristic of smectic order, is obtained.

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I. INTRODUCTION

Type-II superconductors,1 doped Mott insulators,2 quantum Hall systems,8 ultrathin magnetic films,3-5 lipid monolayers,6 and Raleigh-Benard convection,7 are systems that under appropriate conditions present stable phases characterized by the presence of modulated structures. The existence of these modulated structures is well understood on the basis of the fluctuation-induced first-order phase-transition theory (FIFOT), first developed by Brazovskii.9 This scenario predicts that systems in which the spectrum of fluctuations has a minimum in a shell in reciprocal space at a nonzero wave vector, undergo a first-order phase transition driven by fluctuations, in contrast to the second-order transition predicted by mean-field theory. Moreover, the strong degeneracy in the space of fluctuations induces the existence of many metastable structures at low temperatures, and since the experimentally observed structures are in general metastable, dynamical effects become very important. Unfortunately, the dynamical behavior of these systems is far from being understood.

The existence and stability of metastable structures and the nature of the nucleation processes in the context of the Brazovskii scenario were first studied by Hohenberg and Swift.7 They obtained the free-energy barriers to nucleation and the shape and size of critical droplets in the weak-coupling limit. Gross et al.10 compared the predictions of the self-consistent Hartree approximation with direct simulations of the Langevin dynamics, confirming the validity of the approximation.

A classic example where the Brazovskii scenario has gotten strong support, both theoretically and experimentally, is in diblock copolymers.11-13 These systems have interesting technological applications as self-assembling patterning media. Another well-known example of this kind of system is the three-dimensional Coulomb-frustrated ferromagnet. Wolynes et al.14 have shown, using a replica dynamical mean-field theory, that below a characteristic temperature, an exponential number of metastable states appears in the system preventing long-range order. Furthermore, through Monte Carlo simulations15 and also using a mode-coupling analysis for the equilibrium Langevin dynamics of the Coulomb-frustrated ferromagnet, Grousson et al.16 have found an ergodicity-breaking scenario in agreement with the predictions of Wolynes et al. These results resemble the behavior of many glass-former systems, and two theoretical scenarios have been depicted in order to account for its phenomenology.17-18 The relevance of the mode-coupling predictions to the dynamics of the system have nevertheless been questioned by Geissler et al.19

The experimental and theoretical study of thin-film magnetic materials have led to similar questions.20-22 Thin films and quasi-two-dimensional magnetic materials have many important technological applications, for example, in data storage and magnetic sensors.23 In metallic uniaxial ferromagnetic films grown on a metallic substrate, such as CoCu or FeCu, the system develops spontaneous stripe domains upon cooling below the Curie point. This is due to the competition between the exchange ferromagnetic short-range interaction and the antiferromagnetic dipolar one, which is long range.4 In the strong anisotropy or Ising limit, a self-consistent Hartree approximation predicts the presence of a FIFOT for any value of the ratio between the ferromagnetic and antiferromagnetic coupling constants.21 Therefore, the results from Monte Carlo simulations are far from conclusive, suggesting the presence of first-order transitions only for a restricted range of the ratio of the coupling constants.24,25 The dynamics of these systems is also far from clear. Early work from Roland and Desai,26 who did simulations of the Langevin dynamics, concentrated on the early-
time regime, where modulation in the magnetization sets in. Later work with Monte Carlo simulations concentrated in some aspects of the out-of-equilibrium aging dynamics\textsuperscript{27,28} and the growing of stripe domains after a quench.\textsuperscript{29} These works reveal a very rich phenomenology, with the appearance of complex phases reminiscent of liquid crystals, and strong metastability of the dynamics. All these facts point to the necessity of a more systematic study of dynamical aspects of FIFOT.

In this work we solve the Langevin dynamics of a generic model with a scalar-order parameter undergoing a first-order phase transition driven by fluctuations. To characterize the long-time dynamics of the system, we study the fluctuation spectrum close to the wave vector $k_0$ representative of the modulated phases. We solve the dynamical equations in the Hartree approximation and show that, already within this approximation, the dynamics of the system is very rich and departs from the usual ferromagnetic case. We neglect quantum fluctuations at low temperatures, and consequently the Hartree approximation used amounts only to a self-consistent treatment of thermal fluctuations. A key observation is that, as we show in the next section, the spinodal of the high-temperature disordered phase shifts to zero temperature in this approximation, and this has a strong influence on the dynamics after a quench. In agreement with the equilibrium results, we show that the instability of the disordered phase appears only at $T=0$, where the dynamics changes qualitatively. Nevertheless, the relaxation at finite temperature is far from trivial, showing the emergence of domains of stripes, which form a kind of mosaic state on top of the striped equilibrium phase.

The rest of the paper is organized as follows. In Sec. II we present the model and show that, in the static self-consistent approximation, it undergoes a FIFOT. In Sec. III we introduce the Langevin dynamics. In Sec. IV we present the general procedure to calculate the dynamical properties of the system in the Hartree approximation. Sections V and VI are the core of the paper, where the results on correlations and responses are presented. In Section VII we compare our results with previous ones from the literature and discuss its implications and limitations. Some conclusions are presented in Sec. VIII. In two appendices we explain some technical details of the calculations.

II. A MODEL WITH A FLUCTUATION-INDUCED FIRST-ORDER TRANSITION

A classical model that undergoes a FIFOT may be defined by an attractive (ferromagnetic) short-range interaction plus a competing, long-range repulsive (antiferromagnetic) interaction. In the simplest case of a scalar field, one can define an effective Landau-Ginzburg Hamiltonian of the form

$$
\mathcal{H}[\phi] = \int d^d x \left[ \frac{1}{2} \nabla^2 \phi(x) + \frac{r}{2} \phi^2(x) + \frac{\mu}{3} \phi^3(x) \right] + \frac{1}{2\delta} \int d^d x d^d x' \phi(x)J(|x-x'|)\phi(x'),
$$

(1)

where $r<0$ and $\mu>0$. $J(|x-x'|)=J(|\vec{x}-\vec{x}'|)$ represents a repulsive, isotropic, long-range interaction and $\delta$ measures the relative intensity between the attractive and repulsive parts of the Hamiltonian. In the limit $\delta \to \infty$ one recovers the ferromagnetic $O(N)$ model (for $N=1$).\textsuperscript{30–32}

The $(u/4)\phi^4$ term introduces a nonlinearity that makes an exact solution of the model an impossible task. To deal with this nonlinearity, one must consider the introduction of some kind of perturbative analysis. The simplest resummation scheme is the self-consistent Hartree approximation, or large $N$ limit. It consists of replacing one factor $\phi^2$ in the $\phi^4$ term in the Hamiltonian by its average $\langle \phi^2 \rangle$, to be determined self-consistently. There are six ways of choosing the two factors of $\phi$ to be paired in $\langle \phi^2 \rangle$, so the Hamiltonian in the Hartree approximation takes the Gaussian form

$$
\mathcal{H}[\phi] = \frac{1}{2} \int d^d x \left[ \nabla \phi(x)^2 + r \phi^2(x) + g \phi^2(\phi(\phi(x))) \right] + \frac{1}{2\delta} \int d^d x d^d x' \phi(x)J(|\vec{x}-\vec{x}'|)\phi(x'),
$$

(2)

where $g=3u$. Introducing the Fourier transform

$$
\phi(\vec{x}) = \int \frac{d^d k}{(2\pi)^d} e^{i\vec{k}\cdot\vec{x}} \hat{\phi}(\vec{k}),
$$

(3)

$$
\hat{\phi}(\vec{k}) = \int d^d x e^{-i\vec{k}\cdot\vec{x}} \phi(\vec{x}),
$$

(4)

the Hamiltonian takes the form

$$
\mathcal{H}[\phi] = \frac{1}{2} \int \frac{d^d k}{(2\pi)^d} A(k) \hat{\phi}(\vec{k}) \hat{\phi}(-\vec{k})
$$

$$
+ \frac{g}{2} \int \frac{d^d k_1}{(2\pi)^d} \int \frac{d^d k_2}{(2\pi)^d} \int \frac{d^d k_3}{(2\pi)^d} \hat{\phi}(\vec{k}_1) \hat{\phi}(\vec{k}_2) C(\vec{k}_3, -\vec{k}_1 - \vec{k}_2)
$$

$$
= \frac{1}{2} \int \frac{d^d k_1}{(2\pi)^d} \int \frac{d^d k_2}{(2\pi)^d} \hat{\phi}(\vec{k}_1) \left[ A(k_1) \delta_{\vec{k}_1, -\vec{k}_2} + g \int \frac{d^d k}{(2\pi)^d} C(\vec{k}, -\vec{k} - \vec{k}_1 - \vec{k}_2) \right] \hat{\phi}(\vec{k}_2)
$$

$$
\frac{1}{2} \int \frac{d^d k_1}{(2\pi)^d} \int \frac{d^d k_2}{(2\pi)^d} \hat{\phi}(\vec{k}_1) A(\vec{k}_1, \vec{k}_2) \hat{\phi}(\vec{k}_2),
$$

(5)

with

$$
A(\vec{k}_1, \vec{k}_2) = A(k_1) \delta_{\vec{k}_1, -\vec{k}_2} + g \int \frac{d^d k}{(2\pi)^d} C(\vec{k}, -\vec{k} - \vec{k}_1 - \vec{k}_2).
$$

(6)

In the previous expression $A(k) = r + k^2 + 3j(k)/\delta$ and $C(\vec{k}, \vec{k}') = \langle \hat{\phi}(\vec{k}) \hat{\phi}(\vec{k}') \rangle$. Using that $A(\vec{k}_1, \vec{k}_2) = A(-\vec{k}_1, -\vec{k}_2)$ and that $C(\vec{k}, \vec{k}') = C(\vec{k}, \vec{k}') + m_{\vec{k}} m_{\vec{k}'}$, where $m_{\vec{k}} = \langle \hat{\phi}(\vec{k}) \rangle$ and $C(\vec{k}, \vec{k}')$ is the connected correlation function, we get finally the self-consistent Hartree equation for the connected correlator

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A(\vec{k}_1,\vec{k}_2) = \beta^{-1} C^{-1}_c(\vec{k}_1,\vec{k}_2) = A(k_1) \delta_{\vec{k}_1,\vec{k}_2} + g \int \frac{d^d k}{(2\pi)^d} \left[ m m^* + C_c(\vec{k},\vec{k}_1 + \vec{k}_2 - \vec{k}) \right],

(9)

where $\beta=1/k_BT$. In the paramagnetic phase, at high temperatures, all the order parameters $m_i=0$ and the correlation matrix is diagonal, i.e., $C_c(\vec{k},\vec{k})=S_c(\vec{k}) \delta_{\vec{k},\vec{k}}$, with $S_c(\vec{k})$ being the static structure factor. From Eq. (9) we have

$$
\beta^{-1} S_c^{-1}(\vec{k}) = A(k) + g \int \frac{d^d k}{(2\pi)^d} S_c(\vec{k}),
\int \frac{d^d k}{(2\pi)^d} S_c(\vec{k}).
$$

(10)

Introducing the “renormalized mass”

$$
\lambda = r + g \int \frac{d^d k}{(2\pi)^d} S_c(\vec{k}),
$$

(11)

the structure factor becomes

$$
S_c(\vec{k}) = \frac{T}{\lambda + k^2 + \frac{J(k)}{\delta}},
$$

(12)

where we have set $k_B=1$, and the renormalized mass has to be determined self-consistently from

$$
\lambda = r + g T \int \frac{d^d k}{(2\pi)^d} \frac{1}{\lambda + k^2 + \frac{J(k)}{\delta}}.
$$

(13)

An instability in this equation may appear when $\lambda = \lambda_c = -[k_0^2 + J(k_0)/\delta]$, where $k_0$ is the wave vector, which minimizes $A(k)$. Hence, the spinodal temperature $T^*$ is determined by the equation

$$
\beta^* (r^* - \lambda_c) = -g K_d \int_0^\Lambda k^{d-1} \frac{k_0^{-1}}{\lambda_c + k^2 + \frac{J(k)}{\delta}} dk,
$$

(14)

where $K_d$ is the surface of a $d$-dimensional sphere. The integrand in the right-hand side is always positive and has a singularity at $k=k_0$. Thus, the instability will be determined by the leading behavior of that integral, which can be estimated by expanding the denominator of the integrand around $k_0$.

$$
\int_0^\Lambda k^{d-1} \frac{k_0^{-1}}{\lambda_c + k^2 + \frac{J(k)}{\delta}} dk = \frac{1}{2\delta} \int d^d k J(k) \phi(\vec{x},t) + \eta(\vec{x},t).
$$

(15)

(16)

where $\Lambda$ is the critical temperature. The integrand in the right-hand side is always positive and has a singularity at $k=k_0$. Thus, the instability will be determined by the leading behavior of that integral, which can be estimated by expanding the denominator of the integrand around $k_0$.

$$
\int_0^\Lambda k^{d-1} \frac{k_0^{-1}}{\lambda_c + k^2 + \frac{J(k)}{\delta}} dk = \int_{-\epsilon}^{\epsilon} \frac{(k + k_0)^{d-1}}{k_0^2} dk
$$

Therefore, the spinodal temperature always is depressed to zero, that is, $\beta^* r^* \rightarrow -\infty$. The fact that the isotropic phase is metastable at any finite temperature, a characteristic of the self-consistent nature of the fluctuations included in the model, will have important consequences on the dynamics after a quench at low temperatures, as we will show in the next sections. Nevertheless, it can be shown that below a melting temperature, the true equilibrium phase is a modulated one with characteristic wave vector $k_0$. A first-order phase transition driven by fluctuations takes place.

III. Langevin Dynamics

As usual, the Langevin dynamics for the scalar field $\phi(\vec{x},t)$ is defined by

$$
\frac{\partial \phi(\vec{x},t)}{\partial t} = -\frac{\partial H(\phi)}{\partial \phi} + \eta(\vec{x},t),
$$

(17)

with, in addition, the following conditions for the thermal noise:

$$
\langle \eta(\vec{x},t) \rangle = 0,
$$

$$
\langle \eta(\vec{x},t) \eta(\vec{x}',t') \rangle = 2T \delta(\vec{x}-\vec{x}') \delta(t-t').
$$

(18)

In this work, we consider uncorrelated initial conditions

$$
\langle \eta(\vec{x},0) \eta(\vec{x}',0) \rangle = \Delta \delta(\vec{x}-\vec{x}').
$$

(19)

IV. Self-Consistent Hartree Approximation

A. General solution

In our case of interest the dynamical equation reads

$$
\frac{\partial \phi(\vec{x},t)}{\partial t} = \nabla^2 \phi(\vec{x},t) - r(\phi(\vec{x},t) - u) \phi^3(\vec{x},t)
$$

$$
- \frac{1}{2\delta} \int d^d k J(k) \phi(\vec{x},t) + \eta(\vec{x},t).
$$

(20)

(21)

We will extend the previous results for the equilibrium properties to study the dynamics of the system, using the same resummation scheme. In this approximation, the nonlinear term $\phi^3$ is substituted by $3(\phi^2(\vec{x},t)) \phi(\vec{x},t)$ where the average is performed over the initial conditions and noise realizations. In such a way we obtain a linear equation in $\phi$ at the price of introducing a new parameter $\langle \phi^2 \rangle$ to be deter-
mined self-consistently. To proceed, it is useful to go to Fourier space, in which we can write
\[
\frac{\partial \phi(\vec{k},t)}{\partial t} = -[A(k) + I(t)]\phi(\vec{k},t) + \dot{\phi}(\vec{k},t),
\]
where
\begin{align*}
\langle \dot{\phi}(\vec{k},t) \rangle &= 0, \\
\langle \dot{\phi}(\vec{k},t)\dot{\phi}(\vec{k}',t') \rangle &= 2T \delta(\vec{k} + \vec{k}') \delta(t - t'), \\
I(t) &= r + g\phi^2(\vec{r},t), \\
A(\vec{k}) &= k^2 + \frac{1}{2}J(\vec{k}).
\end{align*}

with initial conditions
\[
\langle \dot{\phi}_0(\vec{k}) \rangle = 0, \\
\langle \dot{\phi}_0(\vec{k})\dot{\phi}_0(\vec{k}') \rangle = (2\pi)^d \Delta \delta(\vec{k} + \vec{k}').
\]

From Eq. (19) it is easy to see that the general solution of the model may be written,
\[
\phi(\vec{k},t) = \phi(\vec{k},0)R(\vec{k},t,0) + \int_0^t R(\vec{k},t,t') \dot{\phi}(\vec{k},t')dt',
\]
where
\[
R(\vec{k},t,t') = \frac{Y(t')}{Y(t)} e^{-A(\vec{k})(t-t')},
\]
and \(Y(t) = e^{\int_0^t \dot{\phi} dt} \).

Our main task is now to find a solution for \(Y(t)\), a function that encloses the unknown parameter introduced in the approximation. Following standard procedures\(^{30,31}\) it is easy to show that
\[
\frac{dK(t)}{dt} = 2rK(t) + 2g\Delta f(t) + 4gT\int_0^t dt' f(t - t') K(t'),
\]
where \(K(t) = Y^2(t)\) and
\[
f(t) = \int \frac{d^d k}{(2\pi)^d} e^{-2A(\vec{k})r}.
\]

Equation (26) may be solved by Laplace transformation methods. If \(\tilde{K}(p)\) and \(\tilde{f}(p)\) are the Laplace transforms of \(K(t)\) and \(f(t)\) respectively, then Eq. (26) reduces to
\[
\tilde{K}(p) = \frac{2g\Delta \tilde{f}(p) + K(0)}{p - 2r - 4gT\tilde{f}(p)}.
\]

Technically, the problem has been reduced to the calculation of \(\tilde{f}(p)\), to substitute it in Eq. (28) and to calculate the corresponding Bromwich integral for \(K(t)\). Once \(K(t)\) is known, all the dynamical quantities of the system may be easily calculated from integral relations.

V. CALCULATION OF \(K(t)\)

In this rather technical section, we go through a series of approximations and assumptions, which allow us to compute the function \(K(t)\) in the long time limit. We start the section presenting the approximation used to manage \(A(\vec{k})\). It keeps the necessary ingredients to model a fluctuation-induced first-order phase transition in a completely isotropic system, in the sense that the spectrum of fluctuations depends only on the modulus of the wave vector \(k\) and presents a degeneracy on a spherical shell in \(k\) space around a radius \(k_0\). We then proceed to the calculation of \(f(t)\) and finally \(K(t)\), in the long-time regime. We show that the cases \(T>0\) and \(T=0\) give rise to different physics, in agreement with the static calculations.

A. Approximation for \(A(k)\)

Unfortunately, the analytical calculation of \(\tilde{f}(p)\) for general \(A(\vec{k})\) is a hopeless task. We will simplify it, considering only cases in which \(A(\vec{k})\) depends on the modulus of \(\vec{k}\), \(A(\vec{k})=A(k)\) (isotropic interactions). Since we are interested in the long-time dynamics of the model, and we know that the equilibrium phases are characterized by the existence of a nontrivial wave vector \(k_0 \neq 0\), at which the spectrum of fluctuations has a maximum, it is then natural to develop \(A(k)\) close to \(k_0\),
\[
A(k) = A_0 + \frac{A_2}{2}(k - k_0)^2 + \mathcal{O}[(k - k_0)^3],
\]

where
\[
A_0 = A(k_0), \\
A_2 = \frac{d^2 A}{dk^2} \bigg|_{k=k_0},
\]
with \(A_2 > 0\).

Note that, if \(t\) is large enough, this approximation is valid not only for models with long-range interactions, but in general is a good starting point to study other systems whose spectrum of fluctuations have an isotropic minimum at a nonzero wave vector. Therefore, the reader must keep in mind that the results of the next sections are valid in a context more general than the one represented by the Hamiltonian (1).

From a technical point of view, one may note that \(A_0\) is irrelevant to the dynamical behavior of the system. In fact, from Eq. (19), one can easily see that it is equivalent to a rescaling of \(r\), and therefore to a shift in the critical temperature of the system. Therefore, from now on it will be neglected in our calculations.

B. Results for \(\tilde{f}(p)\)

With the previous assumptions for \(A(k)\), we may write \(f(t)\) as
\[
f(t) = \int \frac{d^dk}{(2\pi)^d} e^{-A_2(k-k_0)^2}, \tag{32}
\]
whose Laplace transform becomes
\[
\tilde{f}(p) = \int \frac{d^dk}{(2\pi)^d} \frac{1}{p + A_2(k-k_0)^2}. \tag{33}
\]

Next we analyze the behavior of this integral when \( p = 0 \). Adding a cutoff factor in the integrals in order to regularize the behavior for large wave vectors,
\[
\tilde{f}(p) = \int \frac{d^dk}{(2\pi)^d} \frac{e^{-(k-k_0)^2/A^2}}{p + A_2(k-k_0)^2}
= \frac{2\pi^{d/2}}{(2\pi)^d \Gamma(d/2)} \int_0^{\infty} dk k^{d-1} e^{-(k-k_0)^2/A^2} \tag{34}
\]
Then, after simple algebra Eq. (34) becomes
\[
\tilde{f}(p) = \frac{2\pi^{d/2}}{(2\pi)^d \Gamma(d/2)} \frac{1}{pA_2^{1/2}k_0} \sum_{j=0}^{(d-1)/2} \left[ \frac{p}{A_2} \right]^{j/2} k_0^{d-1-j} \int_{-A_2k_0}^{A_2k_0} dk e^{-pk^2/2A_2^2} - 1 + k^2, \tag{35}
\]
Expanding the binomial inside the integral we obtain the following expression for general dimensions:
\[
\tilde{f}(p) = \frac{2\pi^{d/2}}{(2\pi)^d \Gamma(d/2)} \frac{1}{pA_2} \sum_{j=0}^{(d-1)/2} \left[ \frac{p}{A_2} \right]^{j/2} k_0^{d-1-j} \int_{-A_2k_0}^{A_2k_0} dk e^{-pk^2/2A_2^2} - 1 + k^2, \tag{36}
\]

with \( d \in \mathbb{Z} \).

At this point two limit cases are possible and will be treated separately below. If \( (A_2/p)^{1/2}|k_0| \rightarrow 0 \) the time scale of observation is such that the stripes are not completely formed, \( p < \frac{1}{4 \pi |k_0|^2} \). In this limit we recover the dynamic properties of the pure ferromagnet for \( k_0 \rightarrow 0 \). On the other hand, if \( (A_2/p)^{1/2}|k_0| \rightarrow \infty \) the stripes are already formed and the interaction among them will be responsible for the dynamical properties of the system. Once this more interesting limit is taken, it is impossible to recover the pure ferromagnetic behavior.

1. Stripes in formation

Defining
\[
F_j(k_0, p) = \left( \frac{p}{A_2} \right)^{j/2} k_0^{d-1-j} \int_{-A_2k_0}^{A_2k_0} dk e^{-pk^2/2A_2^2} - 1 + k^2, \tag{37}
\]
and writing it as a Taylor series expansion, for \( k_0 \rightarrow 0 \): \( F_j(k_0, p) = F_j(0, p) + F'_j(0, p)k_0 + O(k_0^2) \), we get
\[
F_j(0, p) = \begin{cases} \left( \frac{p}{A_2} \right)^{(d-1)/2} & \text{if } j = d - 1 \\ 0 & \text{otherwise}, \end{cases} \tag{38}
\]
and
\[
F'_j(0, p) = \begin{cases} \left( \frac{p}{A_2} \right)^{(d-2)/2} & \text{if } j = d - 2 \\ 0 & \text{otherwise}. \end{cases} \tag{39}
\]

Therefore, up to first order in \( k_0 \), \( F(k_0, p) \) becomes
\[
F_j(k_0, p) = \left( \frac{p}{A_2} \right)^{(d-1)/2} \int_0^{\infty} dk k^{d-1} e^{-|pA_2|k^2/A^2}
+ k_0 \left( \frac{p}{A_2} \right)^{(d-1)/2} \int_0^{\infty} dk \frac{k^{d-1}}{1 + k^2} e^{-|pA_2|k^2/A^2}, \tag{40}
\]
and \( \tilde{f}(p) \) may be written as
\[
\tilde{f}(p) = p^{(d-2)/2} \left[ a + b \left( \frac{A_2}{p} \right)^{1/2} k_0 \right], \tag{41}
\]
with \( a = \frac{1}{4\pi |k_0|^2} \) and \( b = -\frac{1}{4\pi |k_0|^2 A_2} \Gamma(d/2) \).

From Eq. (41) it comes out that the presence of modulated phases appears in the dynamics as a correction in \( \tilde{f}(p) \) to the usual ferromagnetic case.\(^{50}\) One must remember, however, that this is true provided the second term within the brackets is small, i.e., during the formation of the modulated structures.

2. Stripes formed

On the other hand, for the limit \( (A_2/p)^{1/2}|k_0| \rightarrow \infty \), stripes of sizes \( 1/|k_0| \) are already formed, and the dynamical properties of the system are defined by their interactions. The Taylor expansion, for finite \( k_0 \) and \( p \rightarrow 0 \), is written as \( F_j(k_0, p) = F_j(k_0, 0) + F'_j(k_0, 0)p + O(p^2) \). Then,
\[
F_j(k_0, 0) = \begin{cases} k_0^{d-1} \int_0^{\infty} dk / 1 + k^2 = \pi k_0^{d-1} & \text{if } j = 0 \\ 0 & \text{otherwise}, \end{cases} \tag{42}
\]
and developing as before the first-order derivative with respect to \( p \), and taking the limit \( p \rightarrow 0 \), \( \tilde{f}(p) \) becomes
\[
\tilde{f}(p) = \frac{2\pi^{d/2}}{(2\pi)^d \Gamma(d/2)} \left( \frac{A_2}{p} \right)^{1/2} \left[ \pi k_0^{d-1} + A_2 k_0^{-d-3} \int_0^{\infty} dk \frac{k^2}{1 + k^2} e^{-|pA_2|k^2/A^2} - \frac{k_0^{d-2}}{2} \sqrt{\frac{p}{A_2}} \right]. \tag{43}
\]

From the last expression it can be shown that for small \( p \), \( \tilde{f}(p) = a + bp^{-1/2} \) with \( a < 0 \), independently of the system di-
mension. This limit was also explicitly calculated for \(d=1, 2, \) and \(3,\) confirming the series analysis. The calculations are shown in Appendix A.

Summarizing this subsection, \(\tilde{f}(p)\) was calculated in two limiting cases. In the first case, the system is still evolving and the stripes are not formed. The dynamical properties resemble the ones of the pure ferromagnet plus a correction term. Once the stripes are formed, the dynamics changes qualitatively, and one gets that \(\tilde{f}(p)=a+bp^{-1/2}\), independent of the dimensionality. From now on, we will use this expression in future calculations, and only when necessary we will give explicit values for \(a\) and \(b.\)

**C. Function \(K(t)\)**

By definition,

\[
K(t) = \frac{1}{2\pi i} \int_{\gamma \to \infty} dp e^{pt} \tilde{K}(p),
\]

with \(\tilde{K}(p)\) defined by Eq. (28), where the regularization factors in \(\tilde{f}(p)\) can be disregarded in the long time limit. Then

\[
\tilde{K}(p) = \frac{2g\Delta a + 2g\Delta bp^{-1/2} + 1}{p - 2A_0 - 2r - 4gTa - 4gTbp^{-1/2}}.
\]

Because \(\tilde{f}(p)=a+bp^{-1/2}\), \(\tilde{K}(p)\) has a branch point at \(p=0\), and the denominator varies in the domain \((\infty, \infty).\)

Simplifying the notation we can write

\[
\tilde{K}(p) = \frac{A + Bp^{-1/2}}{p - C - Dp^{-1/2}} = \frac{Ap^{1/2} + B}{p^{3/2} - Cp^{1/2} - D},
\]

with \(A=1+2g\Delta a, B=2g\Delta b, C=2r+4gTa,\) and \(D=4gTb.\)

The denominator of Eq. (46) has three poles. Through a careful analysis it is possible to show that one pole is real and positive for all temperatures. The other two are complex conjugate with negative real part. We have to solve

\[
K(t) = \frac{1}{2\pi i} \int_{\gamma \to \infty} dp e^{pt} \frac{Ap^{1/2} + B}{p^{3/2} - Cp^{1/2} - D}
\]

and

\[
K(t) = \frac{1}{2\pi i} \int_{\gamma \to \infty} dp e^{pt} \frac{Ap^{1/2} + B}{(p^{1/2} - x)(p^{1/2} - z)(p^{1/2} - z^*)},
\]

where \(x^2 \in \mathcal{R}, z^2 \in \mathcal{C},\) and \((z^*)^*\) is the complex conjugate of \(z^2.\) After a lengthy computation (see Appendix B), we get

\[
K(t) = \frac{2x(Ax + B)}{(x - z)(x - z^*)} e^{x^2 t} + \frac{2z(Az + B)}{(z - x)(z - z^*)} e^{z^2 t}
\]

\[
+ \frac{2z^*(Az + B)}{(z - x)(z^* - z)} e^{z^2 t} - \frac{1}{\pi} \int_0^\infty dr e^{-rt} \frac{Br^{3/2} + (BC - AD)r^{1/2}}{D^2 + (r^{3/2} + Cr^{1/2})^2}.
\]

Now, one must distinguish carefully the cases \(T>0\) and \(T=0.\) Note, for example, that the real parts of the complex poles are negative even for \(T \to 0,\) while the real pole is always positive, going to zero at \(T=0,\) where the physics changes qualitatively.

1. \(T>0\)

In this case one may neglect the contributions from the complex conjugate poles, because their real parts include decaying exponential functions. On the other hand, the last integral in Eq. (48) may be easily estimated noting that \((r^{3/2} + Cr^{1/2})^2 = r^2 + 2Cr^2 + C^2 r,\) and that for long times \((t \to \infty),\) the dominant contributions will come from \(r \ll 1.\) We end with

\[
\frac{BC - AD}{D^2} \int_0^\infty dr e^{-rt} r^{1/2} = \frac{BC - AD}{D^2} \sqrt{\frac{\pi}{2t^{3/2}}}.
\]

Therefore,

\[
K(t) = \frac{2x(Ax + B)}{(x - z)(x - z^*)} e^{x^2 t} - \frac{BC - AD}{2\sqrt{\pi C} t^{1/2}},
\]

where the last term goes to zero for \(t \to \infty.\)

2. \(T=0\)

In this case one must note that \(x(T) \to T,\) therefore the contribution from the real pole disappears. At the same time, the complex poles converge to a single real pole that gives rise to a decaying exponential function.

Moreover, the expansion used to calculate the last integral in Eq. (48) is not longer valid. Being \(D=0\) one finds that, for large \(t,\)

\[
B \int_0^\infty dr e^{-rt} r^{3/2} + Cr^{1/2} \sim \frac{B}{\sqrt{\pi C} t^{1/2}},
\]

and

\[
K(t) = \frac{Ax - B}{C} \frac{\Gamma(1/2)}{\sqrt{\pi} t^{1/2}},
\]

with \(C<0.\) The first term is consistent with the limit \(T \to 0\) of the two complex poles and is obviously subdominant in this analysis.

Already with these results at hand one must note two important differences with the usual ferromagnetic coarsening. The first one is that here the temperature is a relevant variable, while for \(T>0\) the relaxation is dominated by exponential (paramagnetic) contributions, for \(T=0\) the relaxation is power-like. The second one is that, excluding irrelevant prefactors, the long-time dynamics, for all temperatures, is independent of the system dimensionality.

VI. RESPONSE AND CORRELATION FUNCTIONS

In this section we present the main physical results of the paper, regarding the behavior of correlation and response functions.

As seen in Sec. (4), the two-times response function in Fourier space is given by
\[ R(k,t,t') = \frac{Y(t')}{Y(t)} e^{-i(k)(t-t')} , \]  
\[ C(\tilde{k},t,t') = \Delta e^{-i(1/2)B(k)(t-t')} + 2Te^{-i(1/2)B(k)(t-t')} \times \int_0^{t'} ds e^{i(1/2)B(k)s} \left( 1 + \frac{C_2 e^{-x^2 s}}{2C_1 s^{3/2}} \right)^2 . \]  

Performing the integration in Eq. (59) and setting \( \tau = t - t' \) one gets

\[ C(k,\tau,t') = e^{-i(1/2)B(k)\tau} \left[ \frac{2T}{B(k)} + \left( \Delta - \frac{2T}{B(k)} \right) e^{-B(k)\tau} \right] - \frac{C_2}{C_1} e^{-i(1/2)\tau^2/2} . \]  

The dominant term in this expression is stationary, i.e., depends only on the difference between the longest and the shortest times \( t-t' \). The exponential decay is typical of relaxation in a disordered or paramagnetic phase. The second term within brackets decays exponentially to zero, while the \( 1/\tau^2 \) in the third term reflects the presence of interrupted aging in the system. As a subleading contribution, it can be said that the system ages in a restricted time window, namely for times \( t' < x^{-2} \). As will be shown below, \( x^{-2} \) is proportional to the correlation length and, consequently, it is this length scale which interrupts the aging, restoring a time-translation invariant, equilibrium dynamics.

On the other hand, keeping the stationary part and for \( t = t' \), we obtain the static structure factor

\[ C(\tilde{k}) = \lim_{t \to \infty} C(\tilde{k},t) = \frac{2T}{B(k)} = \frac{2T}{\Delta^2 + A_2(k-k_0)^2} \]  

which, as expected, shows a characteristic peak at \( k = k_0 \).

The correlation function in real space is given by

\[ C(\tilde{x}) = \int_{-\infty}^{\infty} \frac{d^d \tilde{x}}{2\pi^d} C(\tilde{\kappa}) e^{i\tilde{x} \cdot \tilde{\kappa}} . \]  

In \( d \) dimensions,

\[ C(r) = \frac{1}{(2\pi)^{d/2}} \int_0^{\infty} \frac{kd^{d-1}dk}{\sqrt{2\pi} \cos(kr)} \left[ 1 + \frac{4}{(d-1)\pi} \right] \frac{k^{d-1}dk}{x^2 + A_2(k-k_0)^2} , \]  

where \( J_0(x) \) is a Bessel function of the first kind. In the limit \( kr \to \infty \),

\[ C(r) \propto \cos(k_0r - \psi) e^{-r/\xi}. \]  

This integral can be solved using the theorem of residues in the complex plane. The final result is

\[ \xi(T) = \frac{\sqrt{A_2}}{x}, \]  

It can be shown that, at low temperatures, \( x(T) \propto T \), and consequently, the correlation length diverges at \( T \to 0 \) as \( \xi(T) \propto 1/T \).
From these results one can see that after a quench from the disordered phase to a very low temperature the system breaks into regions inside which there is modulated order, or stripes. No long-range order is observed. A transition is approached at $T=0$, where the correlation length diverges and stripe order sets in. An interesting result concerns the behavior in different dimensions. Note that, as $k \rightarrow \infty$, true long-range order is established in $d=1$. But in $d=2$ and $d=3$ only quasi-long-range order exists, with correlations decaying algebraically as $1/r^{1/2}$ in $d=2$ and as $1/r$ in $d=3$. In the next subsection we analyze in more detail the approach to equilibrium and the final equilibrium states at $T=0$.

**B. $T=0$**

For $T=0$ we may neglect the decay in exponential in Eq. (52) and get

$$R(k,t,t') = \left( \frac{t}{t'} \right)^{1/4} e^{-(1/2)(x^2 + A_2(k - k_0)^2)(t-t')}.$$  \hspace{1cm} (67)

Substituting Eq. (67) in Eq. (55) it is easy to prove that

$$C(k,t,t') = \Delta R(k,t,0)R(k,t',0) = \Delta(t')^{1/4} e^{-(A_2(k - k_0)^2)(t-t')}.$$ \hspace{1cm} (68)

and making $t=t'$ we obtain

$$C(k,t) = \frac{\Delta}{W} t^{1/2} e^{-A_2(k - k_0)^2 t}$$ \hspace{1cm} (69)

with $W=[B\Gamma(1/2)]/(\pi C)$. This result implies that the dynamic structure factor shows space-time scaling in the form

$$C(k,t) = t^{a} h((k - k_0)t),$$ \hspace{1cm} (70)

with $a=1/2$ a dynamic growth exponent and $h(x)$ a scaling function. This exponent has been obtained also in an approximate treatment of the Swift-Hohenberg model by Elder et al., but as already discussed in that paper, it was difficult to see it in numerical simulations. It is necessary to attain time scales of the order of millions of iterations.

The behavior in real space depends strongly on dimensionality. For $d=1$ the spatial correlation function has the form

$$C(r,t) = \frac{1}{\sqrt{\pi A_2 W}} \cos(k_0 r) e^{-r^2/4A_2 t}. \hspace{1cm} (71)$$

This result is consistent, for large $t$, with the appearance of modulated and long-ranged positional order. The situation is different in the more studied case of two dimensions. The correlations behave as

$$C(r,t) = \frac{k_0}{\pi A_2 W} \frac{\Delta}{\sqrt{\pi}} \frac{\cos(k_0 r - \pi/4)}{r^{1/2}} \left[ 1 + \frac{1}{8A_2 k_0^2 r^4} \right]. \hspace{1cm} (72)$$

We observe in this case a power-law approach to a state with quasi-long-range order (QLRO), with correlations decaying algebraically in space as $r^{1/2}$.

As a final example of physical interest, the case $d=3$ gives:

$$C(r,t) = \frac{1}{\sqrt{\pi A_2 W}} \frac{\Delta}{2\pi} \frac{k_0}{r} \cos(\pi/2) e^{-r^2/4A_2 t}. \hspace{1cm} (73)$$

In this case the system also shows QLRO but with a different exponent, with correlations decaying as $1/r$. In the next section we discuss the implications of these results and compare them with existing ones.

**VII. DISCUSSION**

The results of the previous section imply very different relaxation dynamics at $T>0$ and at $T=0$. After a quench from an uncorrelated state at high temperature to a low but finite temperature, the asymptotic dynamics is stationary, similar to the relaxation in a paramagnetic or disordered state. Nonstationary effects, like aging, are subdominant, and decay in a finite time scale. This time scale corresponds to the time at which the correlations extend up to a finite correlation length, as shown above. The existence of a finite, temperature-dependent correlation length, together with the isotropy of the interactions, gives rise to a scenario similar to a mosaic of domains. Inside the domains, short-range stripe order sets in, but the orientation of the stripes changes from domain to domain due to the overall isotropy. The stability of the paramagnetic phase until $T=0$ is obtained also in a purely static calculation of the phase diagram in the self-consistent (Hartree) approximation. Nevertheless, the same calculation shows that the disordered phase is only metastable, the stripe phase has a lower free energy below a finite critical temperature, and is thus the true thermodynamic equilibrium of the system at low temperatures. Our calculations show that the Langevin dynamics within the Hartree approximation reproduces this scenario. A quench from a disordered phase to $T > 0$ gives rise to a paramagnetic-like dynamics reflecting the metastability of this phase. One may ask why the ultimate stripe phase with long-range order is not attained in our dynamic calculations. This is probably due to the fact that orientational order is not broken at all. The model is completely isotropic, and also the initial conditions are completely uncorrelated. The emergence of a long-range stripe phase at finite temperatures may be obtained by applying a small symmetry-breaking field or by studying a quench from correlated initial conditions. We are currently studying this last case. Certainly, within the context of the present calculation, different initial conditions can be studied, and different and interesting physics is expected to emerge in each case. Another interesting possibility is to study a completely saturated initial condition, where the field $\phi(x,0)$ is fixed in a large constant value. This case has been analyzed in computer simulations of a uniaxial magnetic film, and shows very interesting memory effects due to the difficulty of the dynamics in overcoming the initial saturated state.

The dynamics, within the present conditions, becomes more interesting at $T=0$, where the disordered state becomes unstable and consequently a striped phase can develop. Our results show the presence of dynamic scaling in the structure factor, Eq. (69), with an exponent $a=1/2$. In computer simulations an exponent $1/4$ has been reported more frequently. However, Elder et al. found an exponent $1/2$ in an analyti-
tical approximation and also in simulations of the Swift-Hohenberg model, in agreement with our results. Furthermore, in their simulations they observe a first regime with a 1/4 exponent, followed by a crossover to an asymptotic 1/2 regime. The time scale of the asymptotic regime turned out to be of the order of $10^5$ iterations of the dynamical equations, and was difficult to attain at the time of that work. At present, this regime should be accessible to a computer simulation. In fact, recent results on the coarsening dynamics of a uniaxial ferromagnet with competing interactions by Gleiser et al., show a crossover from a preasymptotic logarithmic growth to a final power law with exponent 1/2.

The results of the dynamical correlations in real space are dependent on dimensionality. In $d=1$, the system relaxes to a state with long-range positional order. The order parameter is sinusoidally modulated. This final state is expected in $d=1$ because the domain walls can easily accommodate to a long-range sinusoidal pattern. A different situation is expected in higher dimensions, where topological defects induce large energy barriers in the ordering process. In fact, the results show that only quasi-long-range order is present in dimensions two and three, with different exponents characterizing the algebraic decay of correlations, a 1/2 exponent in $d=2$ and an exponent equal to 1 in $d=3$.

In the literature on systems with liquid crystal-like phases one can find many different values for the exponents, and even the very existence of some phases at low temperatures is a matter of debate. It is important to realize that minimal changes in the energy function, like the introduction of a slight anisotropy in one particular direction, can change the symmetry of the Hamiltonian and the universality class of the system. Our results, besides being obtained in a specific approximation on the dynamical equations, correspond to a system with the minimal ingredients to show a fluctuation-induced first-order phase transition. The interaction is strictly isotropic. This, together with the fact that the initial conditions are uncorrelated in space, reflects in the isotropic nature of the final expressions for correlations and responses. This may cause problems, for example, when comparing our results with computer simulations on small lattices, where the very presence of the lattice induces an effective anisotropy in the system behavior. Also, our calculation is limited to a scalar-order parameter with nonconserved dynamics. The interesting case of conserved-order parameter, which applies, for example, in the study of diblock copolymers, can be pursued in the same lines of our present analysis, but quantitative results may be different, specially the value of exponents, as is the case in the well-known pure models (without competition). We think that, already within the self-consistent Hartree approximation, it would be interesting to extend our present analysis to more complex situations, with anisotropies in the interactions or in the initial conditions, and also to systems with vector-order parameters. Detailed computer simulations, although abundant in the literature, have not been systematic in exploring these different possibilities.

**APPENDIX A**

In this work we have calculated within the Hartree approximation the exact long-time dynamics of a model system exhibiting a fluctuation-induced first-order phase transition. We motivate our work starting with a Hamiltonian with short-range ferromagnetic interaction and long-range antiferromagnetic interactions, but our results are valid in general for the long-time dynamics of any system exhibiting fluctuation-induced first-order phase transitions, provided that the spectrum of the fluctuations is isotropic. We present explicit expressions for the time-dependent correlation and response functions and show that the dynamics converges to known static results in the Hartree approximation. Our results show that the dynamics of the system may be decomposed in two stages, first the modulated phases form, and during this stage the dynamics follows the usual coarsening scenario for a ferromagnetic system. The dynamics is dominated by the zero-temperature fixed point and depends on the dimensionality of the system. Then, once the modulated structures are formed, the dynamics changes qualitatively. It then becomes independent of the system dimension and the temperature becomes a relevant variable. For $T>0$ the system exhibits interrupted aging and a standard paramagnetic relaxation for large times, dominated by the presence of a (meta)stable paramagnetic state. At low temperatures domains of stripes are formed. At $T=0$ the correlation length diverges and stripe order sets in.

In this work we have explored only the presence of positional order, through the calculation of the correlations of the field $\phi(\vec{x},t)$. It would be interesting to compute also orientational observables, which are known to be relevant for this kind of system, and give rise to nematic-like order. Other interesting questions that can be addressed starting from the present calculations are the possible nucleation of stripe phases in the paramagnetic state, which eventually should lead to the first-order transition predicted within the static Hartree approximation. Also, the possible presence of freezing in the low-temperature dynamics could be addressed within a refined approximation, such as mode coupling or the self-consistent screening approximation. We are currently working on some of these interesting possibilities.

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Here we show the explicit calculation of $\tilde{f}(p)$ in the limit $p \to 0$ for $d=1$, $d=2$, and $d=3$. We begin from Eq. (36) in each case, and develop the sums and integrals.

1. $d=1$

In this case Eq. (36) reduces to

$$
\tilde{f}(p) = \frac{1}{\pi(p A_2)^{1/2}} \int_{-(A_2/p)^{1/2}|k_0|}^{\infty} \frac{dk}{1+k^2} e^{-pk^2/A_2 A_2^2}.
$$

Now,
\[
\int_{(A_2 p)^{1/2} k_0}^\infty \frac{dk}{1 + k^2} e^{-p k^2 / A_2 \Lambda^2} = \int_{-\infty}^\infty \frac{dk}{1 + k^2} e^{-p k^2 / A_2 \Lambda^2} = \pi - \int_{(A_2 p)^{1/2} k_0}^\infty \frac{dk}{1 + k^2} e^{-p k^2 / A_2 \Lambda^2}. \tag{A2}
\]

The last equality is due to the integrand being an even function. For \(p \to 0\) the last integral gives
\[
\int_{(A_2 p)^{1/2} k_0}^\infty \frac{dk}{1 + k^2} e^{-p k^2 / A_2 \Lambda^2} = \left( \frac{p}{A_2} \right)^{1/2} e^{-|k_0|^2 / |k_0|^2} \Lambda^2 + O(p^{3/2}). \tag{A3}
\]

Then,
\[
\bar{f}(p) = \frac{1}{\pi(p A_2)^{1/2}} \left\{ \pi - \left( \frac{p}{A_2} \right)^{1/2} e^{-|k_0|^2 / |k_0|^2} \Lambda^2 |k_0| + O(p^{3/2}) \right\} = \frac{1}{A_2^{1/2} p^{1/2}} - \frac{e^{-|k_0|^2 / |k_0|^2} \Lambda^2}{\pi A_2 |k_0|} + O(p). \tag{A4}
\]

2. \(d=2\)

In this case Eq. (36) reduces to
\[
\bar{f}(p) = \frac{k_0}{2 \pi(p A_2)^{1/2}} \int_{(A_2 p)^{1/2} k_0}^\infty \frac{dk}{1 + k^2} e^{-p k^2 / A_2 \Lambda^2} \left[ 1 + \left( \frac{p}{A_2} \right)^{1/2} \frac{k}{k_0} \right]. \tag{A5}
\]

Here we have to solve two integrals. The first one was already solved for the case \(d=1\),
\[
\int_{(A_2 p)^{1/2} k_0}^\infty \frac{dk}{1 + k^2} e^{-p k^2 / A_2 \Lambda^2} = \pi - \left( \frac{p}{A_2} \right)^{1/2} e^{-|k_0|^2 / |k_0|^2} \Lambda^2 |k_0| + O(p^{3/2}). \tag{A6}
\]

The second integral is
\[
\int_{(A_2 p)^{1/2} k_0}^\infty \frac{dk}{1 + k^2} e^{-p k^2 / A_2 \Lambda^2} = \int_{-\infty}^\infty \frac{dk}{1 + k^2} e^{-p k^2 / A_2 \Lambda^2} = \int_{(A_2 p)^{1/2} k_0}^\infty \frac{dk k}{1 + k^2} e^{-p k^2 / A_2 \Lambda^2}, \tag{A7}
\]

because the integrand is an odd function. The last integral can be approximated as
\[
\int_{(A_2 p)^{1/2} k_0}^\infty \frac{dk}{1 + k^2} e^{-p k^2 / A_2 \Lambda^2} = \int_{(A_2 p)^{1/2} k_0}^\infty \frac{dk}{k} e^{-p k^2 / A_2 \Lambda^2} \left[ 1 + \frac{1}{k^2} \right] + O(k^{-4}). \tag{A8}
\]

Finally,
\[
\bar{f}(p) = \frac{k_0}{2 \pi A_2^{1/2}} \left\{ \pi p^{-1/2} - \frac{1}{A_2^{1/2}} e^{-|k_0|^2 / A_2^{1/2}} |k_0| + \frac{1}{k_0 A_2^{1/2}} \right\} - \frac{\gamma}{2} - \frac{1}{2} \ln \left( \frac{|k_0|^2}{A_2^{1/2}} \right).	ag{A12}
\]

3. \(d=3\)

In this case,
\[
\bar{f}(p) = \frac{2 \pi^{3/2} k_0^2}{(2 \pi)^3 \Gamma(3/2)(p A_2)^{1/2}} \int_{(A_2 p)^{1/2} k_0}^\infty \frac{dk}{1 + k^2} \times e^{-p k^2 / A_2 \Lambda^2} \left[ 1 + \left( \frac{p}{A_2} \right)^{1/2} \frac{k}{k_0} + \left( \frac{p}{A_2} \right)^{1/2} \frac{k^2}{k_0^2} \right] + O(k^{-4})
\]
\[
= \frac{2 \pi^{3/2} k_0^2}{(2 \pi)^3 \Gamma(3/2)(p A_2)^{1/2}} \left\{ \pi - \left( \frac{p}{A_2} \right)^{1/2} e^{-|k_0|^2 / A_2^{1/2}} |k_0| \right\} + \frac{1}{k_0} \left( \frac{p}{A_2} \right)^{1/2} \left[ - \frac{\gamma}{2} - \frac{1}{2} \ln \left( \frac{|k_0|^2}{A_2^{1/2}} \right) \right].
\]
The numerator has the form

\[ + \frac{1}{k_0^2 A_2} \int_{-(A_2 p)^{1/2} |k_0|}^{\infty} \frac{d k k^{2} e^{-p k^2 A_2^2}}{1 + k^2}. \]  

(A13)

Again, the contribution of the dominant term is of order \( p^{-1/2} \), proving that, in agreement with the series expansion in the text, the behavior of \( f(p) \) is independent of dimensionality.

**APPENDIX B**

For \( \tilde{f}(p) = a + b p^{-1/2} \) we have

\[
K(t) = \frac{1}{2 \pi i} \int_{c-i\infty}^{c+i\infty} d e^{p t} \frac{A p^{1/2} + B}{p^{3/2} - C p^{1/2} - D} = \frac{1}{2 \pi i} \int_{c-i\infty}^{c+i\infty} d e^{p t} \frac{A p^{1/2} + B}{(p^{1/2} - x)(p^{1/2} - z)(p^{1/2} - z^*)},
\]

where \( x^2 \in \mathbb{R}, z^2 \in C, \) and \((z^*)^2\) is the complex conjugate of \( z^2 \). The three poles \( x^2, z^2, \) and \((z^*)^2\) are simple and the residues are

\[
\lim_{p \to x^2} (p - x^2) e^{p t} \tilde{K}(p) = (A x + B) e^{x^2} 2 x \left( x - z \right) \left( x - z^* \right),
\]

\[
\lim_{p \to z^2} (p - z^2) e^{p t} \tilde{K}(p) = (A z + B) e^{z^2} 2 z \left( z - x \right) \left( z - z^* \right).
\]

\[
\int_{C}^{D} d e^{p t} \frac{A p^{1/2} + B}{p^{3/2} - C p^{1/2} - D} = \int_{\infty}^{0} d (r e^{i \varphi}) e^{r e^{i \varphi} t} \frac{A r^{1/2} e^{r^{3/2} i \varphi} + B}{r^{3/2} e^{3 r^{1/2} i \varphi} - C r^{1/2} e^{r^{1/2} i \varphi} - D} = - \int_{\infty}^{0} d r e^{-r t} \frac{B + i A r^{1/2}}{-i r^{3/2} - i C r^{1/2} - D},
\]

(B4)

\[
\int_{F}^{G} d e^{p t} \frac{A p^{1/2} + B}{p^{3/2} - C p^{1/2} - D} = \int_{0}^{\infty} d (r e^{i \varphi}) e^{r e^{i \varphi} t} \frac{A r^{1/2} e^{-r^{3/2} i \varphi} + B}{r^{3/2} e^{-3 r^{1/2} i \varphi} - C r^{1/2} e^{-r^{1/2} i \varphi} - D} = - \int_{0}^{\infty} d r e^{-r t} \frac{B - i A r^{1/2}}{i r^{3/2} + i C r^{1/2} - D},
\]

(B5)

Then,

\[
\int_{C}^{D} + \int_{F}^{G} = \int_{0}^{\infty} d r e^{-r t} \left\{ \frac{B + i A r^{1/2}}{i (r^{3/2} + C r^{1/2})} - D \right\} = \int_{0}^{\infty} d r e^{-r t} \left\{ \frac{B - i A r^{1/2}}{D - i (r^{3/2} + C r^{1/2})} - \frac{B + i A r^{1/2}}{D + i (r^{3/2} + C r^{1/2})} \right\}
\]

\[
= \int_{0}^{\infty} d r e^{-r t} \left[ \frac{D + i (3 r^{3/2} + C r^{1/2}) (B - i A r^{1/2}) - D + i (3 r^{3/2} + C r^{1/2}) (B + i A r^{1/2})}{D^2 + (r^{3/2} + C r^{1/2})^2} \right].
\]

(B6)

The numerator has the form

\[
xy^1 - x^2y = (R x + i J y)(R y - i J x) - (R x - i J x)(R y + i J y) = R x R y - i R x J y + i R y J x + J x J y - i J x J y + i J y J x - R x R y - J x J y = - 2 i R x J y + 2 i R y J x.
\]

(B7)

Then,
\[
\int_D^C + \int_F^G = 2i \int_0^\infty dr e^{-rt} \left[ B(r^{3/2} + Cr^{1/2}) - ADr^{1/2} \right] / D^2 (r^{3/2} + Cr^{1/2})^2 = 2i \int_0^\infty dr e^{-rt} B(r^{3/2} + (BC - AD)r^{1/2}) / D^2 (r^{3/2} + Cr^{1/2})^2, \quad (B8)
\]

and

\[
K(t) = \sum \text{Res} - \frac{1}{2\pi i} \left\{ \int_D^C + \int_F^G \right\}. \quad (B9)
\]